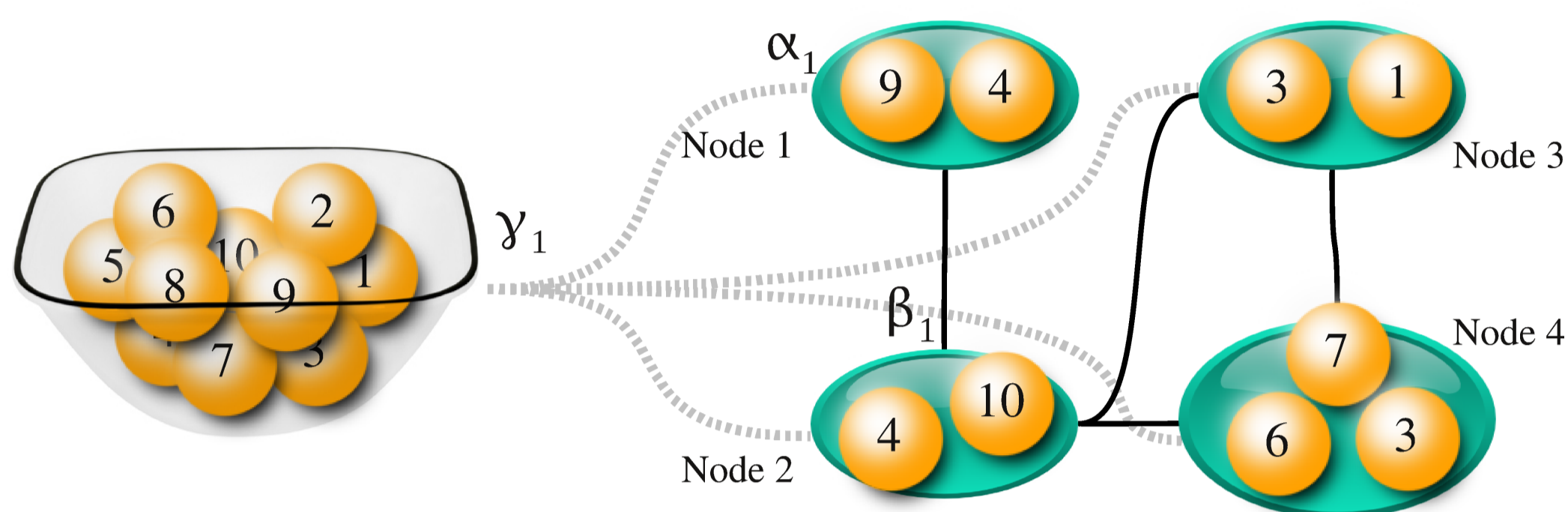


## 1 Selfish Content Replication

- **Replication group:** nodes and users located near the nodes.
  1. Node  $i$  can replicate  $K_i$  objects from the set  $\mathcal{O}$
  2. Objects are accessed by local or neighboring users, the demand for object  $o \in \mathcal{O}$  of the users at node  $i \in N$  is  $w_i^o \in \mathbb{R}_+$
  3. The cost incurred by a user accessing an object is
    - $\alpha_i$ , if the object is replicated locally
    - $\beta_i$ , if the object is replicated in a neighboring node
    - $\gamma_i$ , otherwise
  4. No central authority  $\Rightarrow$  No optimal solution enforced.



- Key questions
  1. Existence of a state where every node is satisfied with the object allocation
  2. Conditions under which the nodes reach such a state updating their decisions myopically

## 2 The model - Replication Game

- **Replication game**  $\langle N, (\mathcal{R}_i), (U_i) \rangle$ :
  - $N$  set of nodes,
  - $\mathcal{R}_i$  set of feasible replication configurations for player  $i$ .
  - $U_i$ : utility function for player  $i$ .
- The nodes choose to replicate objects from the set  $\mathcal{O}$ 
  - $r_i = (r_i^1, \dots, r_i^{|\mathcal{O}|})$ , where  $r_i^o \in \{0, 1\}$  is 1 if object  $o$  is replicated in node  $i$
  - $r_i \in \mathcal{R}_i$  is feasible if  $\sum_o r_i^o \leq K_i$
- Limited interactions between nodes modeled with a **social graph**
  - $\mathcal{N}(i)$  is the set of neighbors of node  $i$ .
- **Utility function:** sum of the cost savings  $U_i(r_i, r_{-i}) = \sum_o U_i^o(r_i^o, r_{-i}^o)$

$$U_i^o(1, r_{-i}) = \begin{cases} w_i^o [\gamma_i - \alpha_i] & \text{if } \prod_{j \in \mathcal{N}(i)} (1 - r_j^o) = 1 \\ w_i^o [\beta_i - \alpha_i] & \text{if } \prod_{j \in \mathcal{N}(i)} (1 - r_j^o) = 0 \end{cases}$$

- **Improvement path:** a sequence of strategy profiles  $r(0), r(1), \dots$ , such that in every step  $t$  there is one player that strictly increases its utility by updating her strategy from  $r_i(t-1)$  to  $r_i(t)$ .
- An update from  $r_i(t-1)$  to  $r_i(t)$  can be

Improvement step	Best reply step
$U_i(r_i(t+1), r_{-i}(t)) > U_i(r_i(t), r_{-i}(t))$	$U_i(r_i(t), r_{-i}(t-1)) \geq U_i(r_i(t-1), r_{-i}(t-1))$ $\forall r_i \in \mathcal{R}_i$

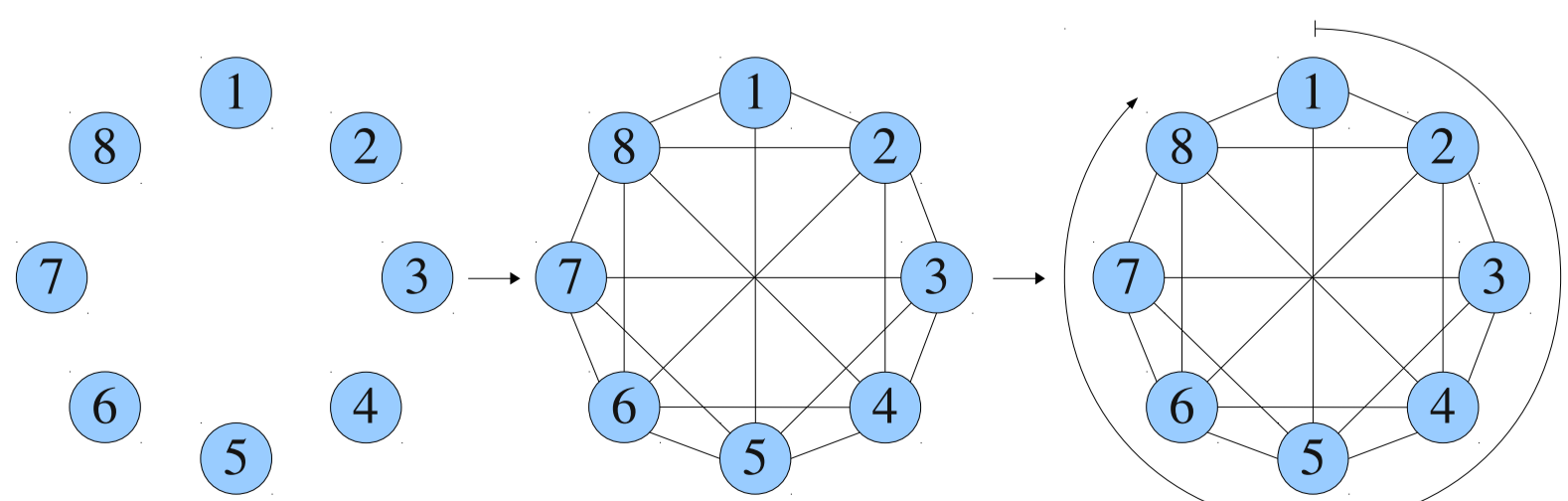
- **Lazy improvement step** of player  $i$ : an improvement step with minimal number of changes among all improvement steps that lead to the same utility.

## 3 Nash Equilibrium - Existence

- **Nash Equilibrium:** a strategy profile  $r^*$  in which every player's strategy is a best reply to the other players' strategies

$$U_i(r_i^*, r_{-i}^*) \geq U_i(r_i, r_{-i}^*) \quad \forall r_i \in \mathcal{R}_i, \forall i \in N.$$

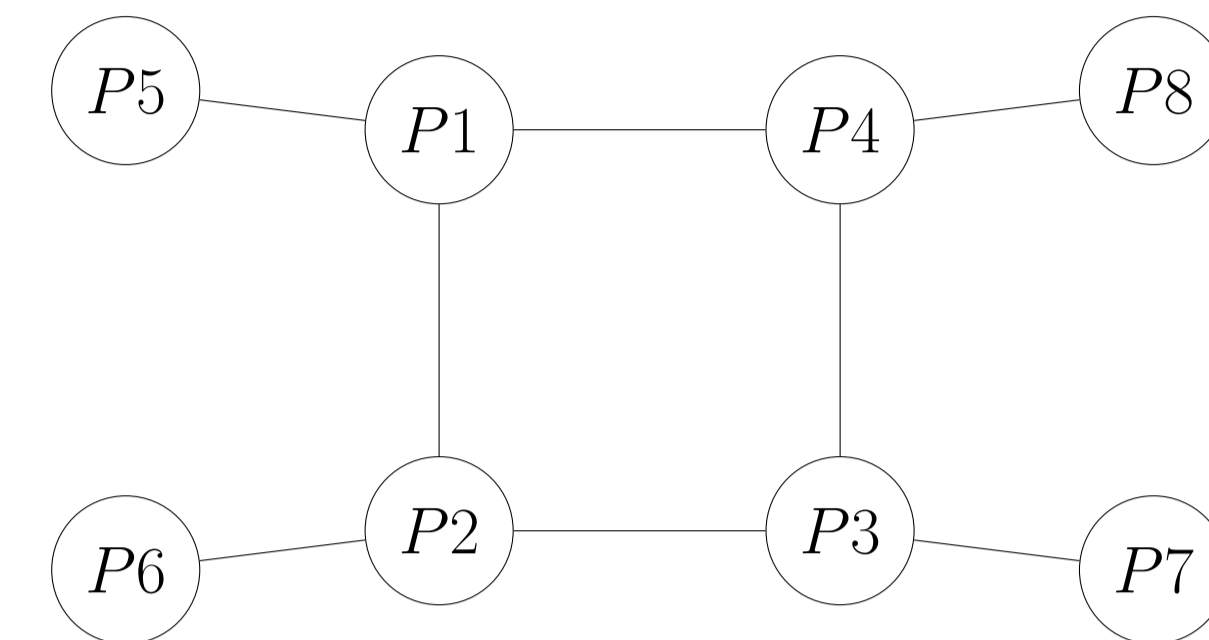
- The following algorithm always ends in a NE:
  1. Play best replies in isolation
  2. Re-arrange the players according to the social graph
  3. Give a chance to play to every player
  4. Play in arbitrary order



- Every graphical replication game possesses a pure strategy Nash equilibrium.

## 4 Nash Equilibrium - Convergence

- **Complete social graph**
  - Every best reply path in a replication game played over a complete social graph is finite.
- **Non-complete social graph**
  - The following graph topology allows a cycle in a best reply path:



The cycle is made of the following sequence of best replies:

Player	P1	P2	P3	P4	P5	P6	P7	P8
Preferences	A<B	B<C	C<D	D<A	B	C	D	A
r(0)	A	B	D	A	B	C	D	A
r(1)	A	B	C	A	B	C	D	A
r(2)	B	B	C	A	B	C	D	A
r(3)	B	B	C	D	B	C	D	A
r(4)	B	C	C	D	B	C	D	A
r(5)	A	C	C	D	B	C	D	A
r(6)	A	C	D	D	B	C	D	A
r(7)	A	B	D	D	B	C	D	A
r(8)	A	B	D	A	B	C	D	A

– If  $K_i = 1 \forall i \in N$

From every strategy profile there exists a best reply path that leads to a NE in a finite number of steps.

↓

The game is weakly acyclic in best replies

– If  $\beta_i = \alpha_i \forall i \in N$

Every lazy improvement path is finite.

## 5 Fast convergence based on graph coloring

**Objective:** relax global synchronization requirement for convergence to NE

- If  $\beta_i = \alpha_i \forall i \in N$

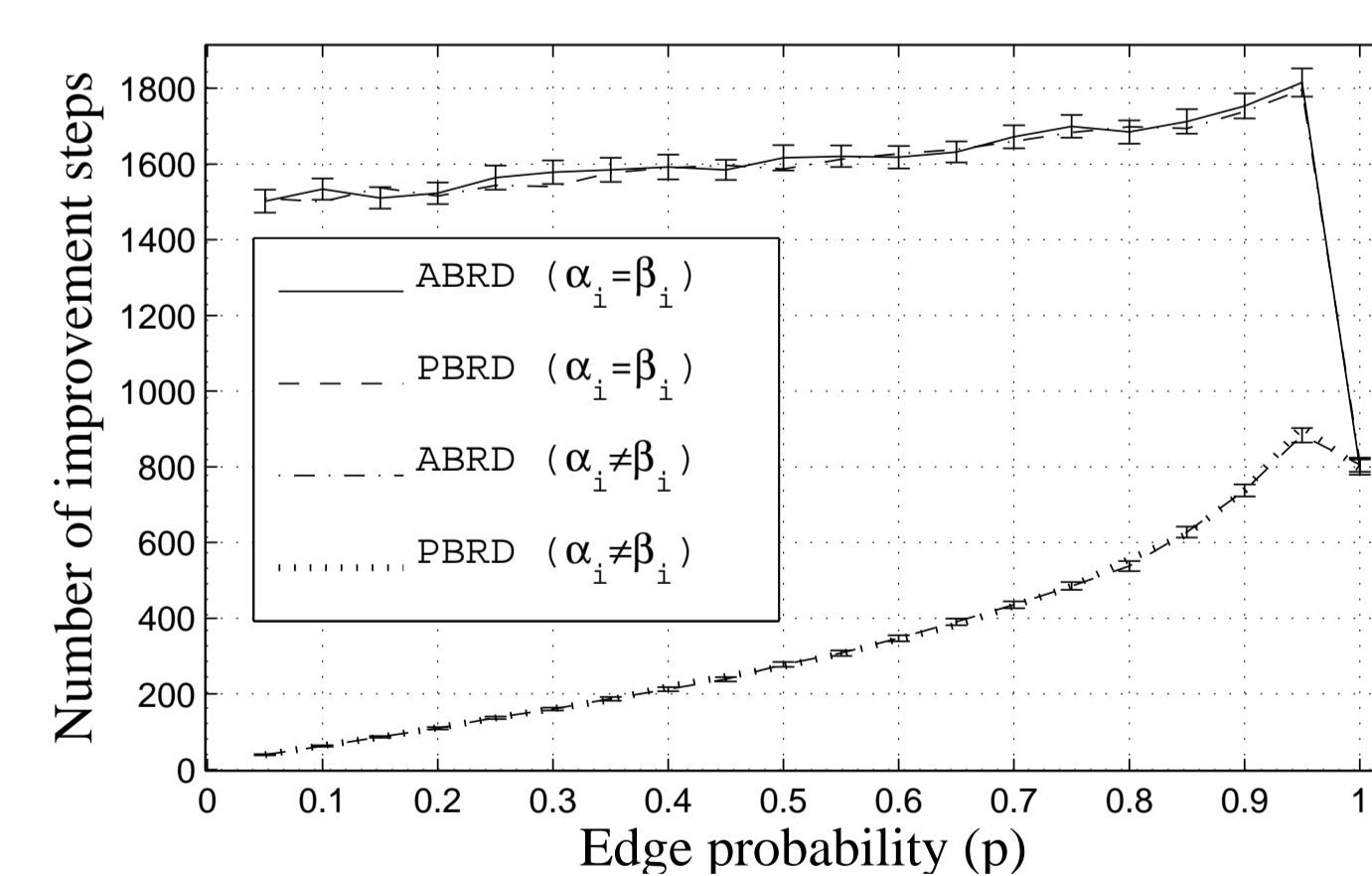
If player  $i$  makes an improvement step at time  $t$  only if no neighboring player  $j \in \mathcal{N}(i)$  makes an improvement step at time  $t$ , then every lazy improvement path is finite.

↓

*Plesiochronous better reply dynamic* (PBRD)

**Objective:** maximize the convergence speed of the PBRD

1. Find a minimum vertex coloring of the social graph
  2. Players with the same color update their strategy simultaneously
- Complexity: find the chromatic number of the graph  $\Rightarrow$  NP-hard
    - Efficient distributed algorithms exist
  - Given a coloring, the number of steps required to reach the NE is significantly smaller than for ABRD



– PBRD significantly faster for sparse social graphs

– The existence of cycles when  $\alpha_i \neq \beta_i$  does not affect the results

– Convergence properties different on a complete social graph than on a sparse graph, in accordance with the complexity of finding the optimal solution

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